







# **Robotic Automation**

**Course Duration: 30 hrs** 

### **Course Objectives:**

- Gain a comprehensive understanding of robotics fundamentals and applications.
- Differentiate between offline and online robot programming approaches.
- Master the ROBO DK software environment and its advanced features.
- Design and implement effective robot simulations and programming strategies.
- Apply ROBO DK to solve real-world industrial robotics challenges.

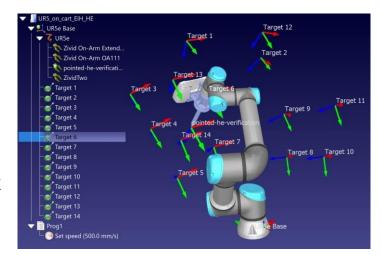
#### **Course Outline:**

#### Introduction to Robo DK

- Overview of Robo DK
  - What is Robo DK?
  - Applications and benefits of Robo DK
  - System requirements and installation
- User Interface and Navigation
  - Exploring the Robo DK interface
  - Understanding the main components and their functions
  - Navigating through the software effectively

#### **Robot Modeling and Simulation**

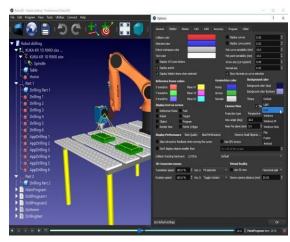
- Fundamentals of Robot Modeling
  - Concepts of robot representation in Robo DK
  - Creating robot models from scratch
  - Importing robot models from CAD files







- Simulating Robot Motion and Interactions
  - Setting up simulation environments
  - Simulating robot motion and interactions with objects
  - Analyzing and debugging simulation results



#### **Programming with Robo DK**

- Introduction to Robo DK Programming
  - Programming languages and tools supported by Robo DK Basic programming concepts and syntax.
  - Writing simple RoboDK programs
- Programming Robot Motion and Interactions
  - Programming robot movement trajectories
  - Controlling robot joints and actuators.
  - Programming robot interactions with sensors and external devices

#### Advanced Topics in Robo DK

- Error Handling and Debugging
  - Identifying and troubleshooting errors in Robo DK programs
  - Using debugging tools to locate and fix errors.
  - Implementing error-handling techniques
  - Integration of Sensors and External Devices
    - Understanding sensor types and data acquisition
    - Integrating sensors into Robo DK simulations
    - Communicating with external devices using Robo DK





## **Deployment and Application**

- Preparing Robo DK Projects for Deployment
  - Organizing and optimizing Robo DK projects
  - Ensuring project compatibility with different environments
  - Packaging and distributing Robo DK projects
- Applications of Robo DK in Various Fields
  - Robo DK in robotics research and development
  - Robo DK in industrial automation and manufacturing
  - Robo DK in education and training

